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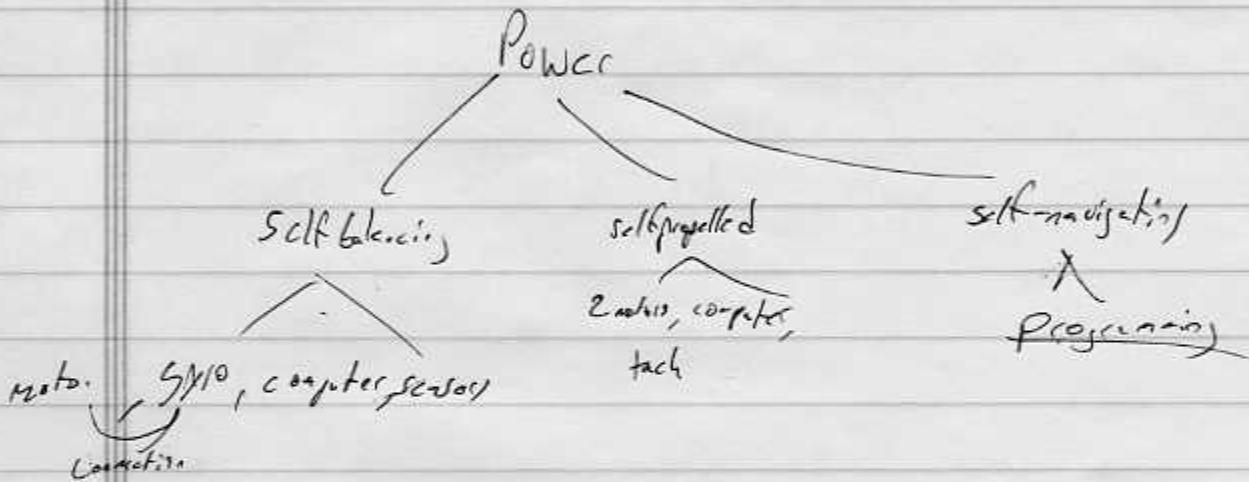
Requirements

- self-balancing
- self-propelled
- self-navigating

Navigation

- object detection & avoidance
- Point A to Point B
- Remote

Arduino



Bike

larger wheel at